printer.cfg：

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# BED

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[heater\_bed]

heater\_pin: BED\_OUT

sensor\_pin: BED\_TEMP

sensor\_type: ATC Semitec 104GT-2

control: watermark

min\_temp: 0

max\_temp: 100 ##Limit the maximum temperature. If the set value is exceeded, an error will be reported and the operation will be stopped

max\_power: 0.5 ##Limited heating power, 0. x represents percentage, 0.5 represents 50% power

The original FLY version is set to the maximum temperature of 200 degrees. The young version hot bed is heated faster, which may cause danger if the heating is too high. Now the maximum temperature is 100 degrees, and the heating power is 50%

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[tmc2209 stepper\_x]

uart\_pin: X\_CS

run\_current: 0.800

interpolate: False

stealthchop\_threshold:200 #Mute threshold to reduce motor running noise, recommended between 100-200

[tmc2209 stepper\_y]

uart\_pin: Y\_CS

run\_current: 0.800

interpolate: False

stealthchop\_threshold:200 #Mute threshold to reduce motor running noise, recommended between 100-200

[tmc2209 stepper\_z]

uart\_pin: Z\_CS

run\_current: 0.4500 #The operating current of Axis Z is changed from 0.8 to 0.45. High current is not required for Axis Z to avoid serious heating

interpolate: False

[tmc2209 extruder]

uart\_pin: E\_CS

run\_current: 0.4500 #The youth version is an ordinary motor. The current is changed from 0.8 to 0.45 to avoid serious heating

interpolate: False